

Global backward error analyses for polynomial eigenvalue problems solved via linearizations

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joint work with **Piers Lawrence** (KU Leuven, Belgium),
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- We consider a **general** $m \times n$ **matrix polynomial**, square or rectangular, regular or singular,

$$P(\lambda) = P_d \lambda^d + \cdots + P_1 \lambda + P_0, \quad P_i \in \mathbb{F}^{m \times n},$$

with $\mathbb{F} = \mathbb{R}$ or $\mathbb{F} = \mathbb{C}$,

- and we assume that its **complete eigenstructure**
- has been computed by applying a **backward stable algorithm**
- to a **strong linearization** $\mathcal{L}(\lambda)$ of $P(\lambda)$
- that allows us to **recover the minimal indices** of $P(\lambda)$ from those of $\mathcal{L}(\lambda)$ via **uniform shifts**.
- In this talk, we restrict most of the results to the **new wide class of block Kronecker linearizations**.

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- 3 Block Kronecker pencils
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Definition

The complete eigenstructure of an $m \times n$ matrix polynomial $P(\lambda)$ is given by:

- its **finite eigenvalues**, together with their **elementary divisors**,
- its **infinite eigenvalue**, together with its **elementary divisors**,
- $n - r$ **right minimal indices** $\varepsilon_1, \dots, \varepsilon_{n-r}$, and
- $m - r$ **left minimal indices** $\eta_1, \dots, \eta_{m-r}$,

where r is the rank of $P(\lambda)$.

Remark

The complete eigenstructure is composed by

- the **regular** structure \rightarrow eigenvalues,
- the **singular** structure \rightarrow minimal indices.

Minimal indices only appear in **singular polynomials**, i.e., either rectangular or square with $\det P(\lambda) \equiv 0$. Other polynomials are called **regular**.

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- A **linearization** for $P(\lambda) = P_d \lambda^d + \cdots + P_1 \lambda + P_0$ is a **linear matrix polynomial (or matrix pencil)** $\mathcal{L}(\lambda)$, such that,

$$U(\lambda) \mathcal{L}(\lambda) V(\lambda) = \begin{bmatrix} I_s & \\ & P(\lambda) \end{bmatrix} \quad (U(\lambda), V(\lambda) \text{ unimodular}).$$

$P(\lambda)$ and $\mathcal{L}(\lambda)$ have the same finite elementary divisors.

- $\mathcal{L}(\lambda)$ is a “strong linearization” if, **in addition**, $\text{rev } \mathcal{L}(\lambda)$ is a linearization for $\text{rev } P(\lambda)$, where $\text{rev } P(\lambda) := P_0 \lambda^d + \cdots + P_{d-1} \lambda + P_d$.

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Introduction. “EXAMPLE” of strong linearization: “Frobenius form”

The **Frobenius companion form** of the $m \times n$ matrix polynomial $P(\lambda) = P_d\lambda^d + \cdots + P_1\lambda + P_0$ is

$$C_1(\lambda) := \begin{bmatrix} \lambda P_d + P_{d-1} & P_{d-2} & \cdots & P_1 & P_0 \\ -I_n & \lambda I_n & & & \\ & \ddots & \ddots & & \\ & & \ddots & \lambda I_n & \\ & & & -I_n & \lambda I_n \end{bmatrix}$$

Theorem ($C_1(\lambda)$ is much more than a strong linearization!!)

- (a) If $0 \leq \varepsilon_1 \leq \cdots \leq \varepsilon_p$ are the right minimal indices of $P(\lambda)$, then the right minimal indices of $C_1(\lambda)$ are $\varepsilon_1 + d - 1 \leq \cdots \leq \varepsilon_p + d - 1$.
- (b) If $0 \leq \eta_1 \leq \cdots \leq \eta_q$ are the left minimal indices of $P(\lambda)$, then the left minimal indices of $C_1(\lambda)$ are $\eta_1 \leq \cdots \leq \eta_q$.

Example of strong linearization whose right (resp. left) minimal indices allow us to recover the ones of the polynomial via uniform shifts.

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Example of strong linearization whose right (resp. left) minimal indices allow us to recover the ones of the polynomial via uniform shifts.

- There are **“backward stable” algorithms that compute the complete eigenstructure of any matrix pencil:**
 - 1 QZ algorithm for regular pencils (Moler & Stewart, 1973).
 - 2 Staircase or GUPTRI algorithm for singular pencils (Van Dooren, 1979; Demmel-Kågström, 1993).
- They can be applied to **strong linearizations $\mathcal{L}(\lambda)$ of a matrix polynomial $P(\lambda)$** and
- if **such linearizations enjoy known uniform shifting relations for the minimal indices**, then
- **these algorithms allow us to compute the complete eigenstructure of $P(\lambda)$** , even in the singular case.
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Introduction: Backward stable algorithms on strong linearizations (II)

- *The computed complete eigenstructure of $\mathcal{L}(\lambda)$ is the exact complete eigenstructure of a matrix pencil $\mathcal{L}(\lambda) + \Delta\mathcal{L}(\lambda)$ such that*

$$\frac{\|\Delta\mathcal{L}(\lambda)\|_F}{\|\mathcal{L}(\lambda)\|_F} = O(\mathbf{u}),$$

where $\mathbf{u} \approx 10^{-16}$ is the unit roundoff and

- $\|\cdot\|_F$ is the Frobenius norm, i.e., for any matrix polynomial

$$\|Q_k\lambda^k + \cdots + Q_1\lambda + Q_0\|_F = \sqrt{\|Q_k\|_F^2 + \cdots + \|Q_1\|_F^2 + \|Q_0\|_F^2}.$$

- But, does this imply that (after shifting properly the minimal indices) the computed complete eigenstructure of $P(\lambda)$ is the exact complete eigenstructure of a matrix polynomial of the same degree $P(\lambda) + \Delta P(\lambda)$ such that

$$\frac{\|\Delta P(\lambda)\|_F}{\|P(\lambda)\|_F} = O(\mathbf{u}) ??$$

- For solving this question, we pose the following **theoretical problems** of matrix perturbation theory.

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To solve the following matrix perturbation problems

- **Data:**

- 1 Matrix polynomial $P(\lambda)$ of degree d .
- 2 Strong linearization $\mathcal{L}(\lambda)$ of $P(\lambda)$ enjoying uniform shift-relations for the minimal indices.
- 3 Perturbation pencil $\Delta\mathcal{L}(\lambda)$.

- **Problem 1:** To establish conditions on $\|\Delta\mathcal{L}(\lambda)\|_F$ such that $\mathcal{L}(\lambda) + \Delta\mathcal{L}(\lambda)$ is a strong linearization for some matrix polynomial $P(\lambda) + \Delta P(\lambda)$ of degree d , and such that

- **Problem 2:** the shift-relations between minimal indices of $\mathcal{L}(\lambda) + \Delta\mathcal{L}(\lambda)$ and $P(\lambda) + \Delta P(\lambda)$ are equal to those between $\mathcal{L}(\lambda)$ and $P(\lambda)$.

- **Problem 3:** To prove a perturbation bound

$$\frac{\|\Delta P(\lambda)\|_F}{\|P(\lambda)\|_F} \leq C_{P,\mathcal{L}} \frac{\|\Delta\mathcal{L}(\lambda)\|_F}{\|\mathcal{L}(\lambda)\|_F},$$

with $C_{P,\mathcal{L}}$ a number depending on $P(\lambda)$ and $\mathcal{L}(\lambda)$.

- For those $P(\lambda)$ and $\mathcal{L}(\lambda)$ s.t. $C_{P,\mathcal{L}}$ is moderate, to use backward stable algorithms on $\mathcal{L}(\lambda)$ gives backward stability for $P(\lambda)$, i.e., from the polynomial point of view.

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- **Problem 1:** To establish conditions on $\|\Delta\mathcal{L}(\lambda)\|_F$ such that $\mathcal{L}(\lambda) + \Delta\mathcal{L}(\lambda)$ is a strong linearization for some matrix polynomial $P(\lambda) + \Delta P(\lambda)$ of degree d , and such that

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$$\frac{\|\Delta P(\lambda)\|_F}{\|P(\lambda)\|_F} \leq C_{P,\mathcal{L}} \frac{\|\Delta\mathcal{L}(\lambda)\|_F}{\|\mathcal{L}(\lambda)\|_F},$$

with $C_{P,\mathcal{L}}$ a number depending on $P(\lambda)$ and $\mathcal{L}(\lambda)$.

- For those $P(\lambda)$ and $\mathcal{L}(\lambda)$ s.t. $C_{P,\mathcal{L}}$ is moderate, to use backward stable algorithms on $\mathcal{L}(\lambda)$ gives backward stability for $P(\lambda)$, i.e., from the polynomial point of view.

To solve the following matrix perturbation problems

- **Data:**

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...has a number of key features which are not present in any other analyses published so far:

- 1 for the first time, it is NOT a first order analysis, since it is a rigorous analysis valid for perturbations $\Delta\mathcal{L}(\lambda)$ of finite norm,
- 2 it provides very detailed bounds, and not just vague big-O bounds as other analyses do,
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There are just a few: **only first order results, only for Frobenius linearizations or their counterparts in other bases**, often only valid for regular polynomials, or do not pay attention to minimal indices...

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We mention briefly **weaker “local” backward analyses valid only** for regular matrix polynomials and for **each particular computed eigenpair**, i.e., **with a different perturbation for each eigenpair**:

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Two fundamental auxiliary matrix polynomials in this talk

$$L_k(\lambda) := \begin{bmatrix} -1 & \lambda & & & \\ & -1 & \lambda & & \\ & & \ddots & \ddots & \\ & & & -1 & \lambda \end{bmatrix} \in \mathbb{F}[\lambda]^{k \times (k+1)},$$
$$\Lambda_k(\lambda)^T := [\lambda^k \quad \lambda^{k-1} \quad \dots \quad \lambda \quad 1] \in \mathbb{F}[\lambda]^{1 \times (k+1)},$$

and their **Kronecker products** by identities

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The **Frobenius companion form** of the $m \times n$ matrix polynomial $P(\lambda) = P_d \lambda^d + \dots + P_1 \lambda + P_0$ is

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Definition and key properties of Block Kronecker Pencils

Definition

Let $\lambda M_1 + M_0$ be an arbitrary pencil. Then any pencil of the form

$$\mathcal{L}(\lambda) = \left[\begin{array}{c|c} \underbrace{\lambda M_1 + M_0}_{(\varepsilon+1)n} & \underbrace{L_\eta(\lambda)^T \otimes I_m}_{\eta m} \\ \hline L_\varepsilon(\lambda) \otimes I_n & 0 \end{array} \right] \begin{array}{l} \} (\eta+1)m \\ \} \varepsilon n \end{array},$$

is called a **block Kronecker pencil** (one-block row and column cases included).

Theorem (key theorem of block Kronecker pencils)

Any block Kronecker pencil $\mathcal{L}(\lambda)$ is a *strong linearization* of the matrix polynomial

$$Q(\lambda) := (\Lambda_\eta(\lambda)^T \otimes I_m)(\lambda M_1 + M_0)(\Lambda_\varepsilon(\lambda) \otimes I_n) \in \mathbb{F}[\lambda]^{m \times n},$$

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- Let $P(\lambda) = \sum_{k=0}^d P_k \lambda^k \in \mathbb{F}[\lambda]^{m \times n}$,
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- let us consider M_0 and M_1 partitioned into $(\eta + 1) \times (\varepsilon + 1)$ blocks each of size $m \times n$.

If the sum of the blocks on the $(d - k)$ th block antidiagonal of M_0 plus the sum of the blocks on the $(d - k + 1)$ th block antidiagonal of M_1 is equal to P_k , for $k = 0, \dots, d$,

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Examples of block Kronecker pencils (I)

$$P(\lambda) = \lambda^5 P_5 + \lambda^4 P_4 + \lambda^3 P_3 + \lambda^2 P_2 + \lambda P_1 + P_0 \in \mathbb{F}[\lambda]^{m \times n}$$

$$\left[\begin{array}{ccc|cc} \lambda P_5 + P_4 & 0 & 0 & -I_m & 0 \\ 0 & \lambda P_3 + P_2 & 0 & \lambda I_m & -I_m \\ 0 & 0 & \lambda P_1 + P_0 & 0 & \lambda I_m \\ \hline -I_n & \lambda I_n & 0 & 0 & 0 \\ 0 & -I_n & \lambda I_n & 0 & 0 \end{array} \right]$$

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for any matrices A and B .

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A “hidden” structure in block Kronecker pencils

$$\mathcal{L}(\lambda) = \left[\begin{array}{c|c} \lambda M_1 + M_0 & L_\eta(\lambda)^T \otimes I_m \\ \hline L_\varepsilon(\lambda) \otimes I_n & 0 \end{array} \right]$$

- $L_\varepsilon(\lambda) \otimes I_n$ and $L_\eta(\lambda) \otimes I_m$ are particular instances of **minimal bases** with all their row degrees equal to 1.
- **Reminder:** $Q(\lambda) \in \mathbb{F}[\lambda]^{m \times n}$ with $m < n$ is a **minimal basis** with all its row degrees equal if and only if the complete eigenstructure of $Q(\lambda)$ consists of only $n - m$ right minimal indices.
- $\Lambda_\varepsilon(\lambda)^T \otimes I_n$ and $\Lambda_\eta(\lambda)^T \otimes I_m$ are also **minimal bases** with all their row degrees equal to ε and η , respectively.
- Moreover, these pairs of minimal bases are “**dual**” each other, i.e.,

$$\begin{aligned} (L_\varepsilon(\lambda) \otimes I_n) (\Lambda_\varepsilon(\lambda) \otimes I_n) &= 0, & \text{(a pair “dual” min. bases)} \\ (L_\eta(\lambda) \otimes I_m) (\Lambda_\eta(\lambda) \otimes I_m) &= 0. & \text{(another pair “dual” min. bases)} \end{aligned}$$

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Definition

A matrix pencil

$$\mathcal{L}(\lambda) = \begin{bmatrix} M(\lambda) & K_2(\lambda)^T \\ K_1(\lambda) & 0 \end{bmatrix}$$

is a **strong block minimal bases pencil** if

- $K_1(\lambda)$ and $K_2(\lambda)$ are minimal bases with all their row degrees equal to 1,
- the row degrees of a minimal basis dual to $K_1(\lambda)$ are all equal, and
- the row degrees of a minimal basis dual to $K_2(\lambda)$ are all equal.

Theorem (key theorem on strong block minimal bases pencils)

Any strong block minimal bases pencil $\mathcal{L}(\lambda)$ is a **strong linearization** of the matrix polynomial

$$Q(\lambda) := N_2(\lambda)M(\lambda)N_1(\lambda)^T,$$

where $N_1(\lambda)$ (resp. $N_2(\lambda)$) is a **minimal basis dual to $K_1(\lambda)$** (resp. $K_2(\lambda)$). The **right minimal indices** of $\mathcal{L}(\lambda)$ are those of $Q(\lambda)$ shifted by $\deg(N_1)$, and the **left minimal indices** of $\mathcal{L}(\lambda)$ are those of $Q(\lambda)$ shifted by $\deg(N_2)$.

Definition

A matrix pencil

$$\mathcal{L}(\lambda) = \begin{bmatrix} M(\lambda) & K_2(\lambda)^T \\ K_1(\lambda) & 0 \end{bmatrix}$$

is a **strong block minimal bases pencil** if

- $K_1(\lambda)$ and $K_2(\lambda)$ are minimal bases with all their row degrees equal to 1,
- the row degrees of a minimal basis dual to $K_1(\lambda)$ are all equal, and
- the row degrees of a minimal basis dual to $K_2(\lambda)$ are all equal.

Theorem (key theorem on strong block minimal bases pencils)

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Why are strong block minimal bases pencils interesting?

- **For us in this talk**, because they include “sufficiently small” (but not necessarily infinitesimal) **perturbations of block Kronecker pencils** that preserve the 0 block in 2×2 position, that preserve the shift relationships between minimal indices, and **for which the corresponding perturbed matrix polynomial is known in terms of perturbations of dual minimal bases**.
- **In general**, they unify and simplify the theory of many Fiedler-type linearizations, even for polynomials in non-monomial bases, and display structures transparently. (Not in this talk, **still in development**, Bueno, FMD, Fassbender, Lawrence, Noferini, Pérez, Shayanfar, Robol, Vandebril, Van Dooren ...)

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- 1 Introduction
- 2 Goals of the talk
- 3 Block Kronecker pencils
- 4 Strong block minimal bases pencils
- 5 The solution of the perturbation problem**
- 6 Conclusions

Theorem

Let $\mathcal{L}(\lambda)$ be a block Kronecker pencil for $P(\lambda) = \sum_{i=0}^d P_i \lambda^i \in \mathbb{F}[\lambda]^{m \times n}$, i.e.,

$$\mathcal{L}(\lambda) = \left[\begin{array}{c|c} \lambda M_1 + M_0 & L_\eta(\lambda)^T \otimes I_m \\ \hline L_\varepsilon(\lambda) \otimes I_n & 0 \end{array} \right].$$

If $\Delta\mathcal{L}(\lambda)$ is any pencil with the same size as $\mathcal{L}(\lambda)$ and such that

$$\|\Delta\mathcal{L}(\lambda)\|_F < \left(\frac{\pi}{16}\right)^2 \frac{1}{d^{5/2}} \frac{1}{1 + \|\lambda M_1 + M_0\|_F},$$

then $\mathcal{L}(\lambda) + \Delta\mathcal{L}(\lambda)$ is a strong linearization of a matrix poly $P(\lambda) + \Delta P(\lambda)$ with grade d and such that

$$\frac{\|\Delta P(\lambda)\|_F}{\|P(\lambda)\|_F} \leq 68 d^{5/2} \frac{\|\mathcal{L}(\lambda)\|_F}{\|P(\lambda)\|_F} (1 + \|\lambda M_1 + M_0\|_F + \|\lambda M_1 + M_0\|_F^2) \frac{\|\Delta\mathcal{L}(\lambda)\|_F}{\|\mathcal{L}(\lambda)\|_F}.$$

In addition, the right (resp. left) minimal indices of $\mathcal{L}(\lambda) + \Delta\mathcal{L}(\lambda)$ are those of $P(\lambda) + \Delta P(\lambda)$ shifted by ε (resp. η), i.e., the shift relations are preserved.

The main perturbation theorem (II)

Theorem

Let $\mathcal{L}(\lambda)$ be a block Kronecker pencil for $P(\lambda) = \sum_{i=0}^d P_i \lambda^i \in \mathbb{F}[\lambda]^{m \times n}$ with $\eta = 0$ or $\varepsilon = 0$, i.e., with the form

$$\mathcal{L}(\lambda) = \left[\begin{array}{c} \lambda M_1 + M_0 \\ L_\varepsilon(\lambda) \otimes I_n \end{array} \right] \quad \text{or} \quad \mathcal{L}(\lambda) = \left[\begin{array}{c|c} \lambda M_1 + M_0 & L_\eta(\lambda)^T \otimes I_m \end{array} \right].$$

If $\Delta\mathcal{L}(\lambda)$ is any pencil with the same size as $\mathcal{L}(\lambda)$ and such that

$$\|\Delta\mathcal{L}(\lambda)\|_F < \frac{\pi}{12 d^{3/2}},$$

then $\mathcal{L}(\lambda) + \Delta\mathcal{L}(\lambda)$ is a strong linearization of a matrix poly $P(\lambda) + \Delta P(\lambda)$ with grade d and such that

$$\frac{\|\Delta P(\lambda)\|_F}{\|P(\lambda)\|_F} \leq 4d \frac{\|\mathcal{L}(\lambda)\|_F}{\|P(\lambda)\|_F} (1 + \|\lambda M_1 + M_0\|_F) \frac{\|\Delta\mathcal{L}(\lambda)\|_F}{\|\mathcal{L}(\lambda)\|_F}.$$

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How are these theorems proved? STEP 1. Restoring the zero block.

The perturbation destroys the $(2, 2)$ -zero block

$$\mathcal{L}(\lambda) + \Delta\mathcal{L}(\lambda) = \left[\begin{array}{c|c} \lambda M_1 + M_0 + \Delta\mathcal{L}_{11}(\lambda) & L_\eta(\lambda)^T \otimes I_m + \Delta\mathcal{L}_{12}(\lambda) \\ \hline L_\varepsilon(\lambda) \otimes I_n + \Delta\mathcal{L}_{21}(\lambda) & \Delta\mathcal{L}_{22}(\lambda) \end{array} \right].$$

Our first step restores the $(2, 2)$ -zero block via a strict equivalence close to the identity

$$\begin{aligned} & \left[\begin{array}{cc} I_{(\eta+1)m} & 0 \\ C & I_{\varepsilon n} \end{array} \right] (\mathcal{L}(\lambda) + \Delta\mathcal{L}(\lambda)) \left[\begin{array}{cc} I_{(\varepsilon+1)n} & D \\ 0 & I_{\eta m} \end{array} \right] \\ &= \left[\begin{array}{cc} \lambda M_1 + M_0 + \Delta\mathcal{L}_{11}(\lambda) & L_\eta(\lambda)^T \otimes I_m + \Delta\tilde{\mathcal{L}}_{12}(\lambda) \\ L_\varepsilon(\lambda) \otimes I_n + \Delta\tilde{\mathcal{L}}_{21}(\lambda) & 0 \end{array} \right] =: \mathcal{L}(\lambda) + \Delta\tilde{\mathcal{L}}(\lambda). \end{aligned}$$

- C and D are solutions of an **underdetermined quadratic system of two matrix equations** whose existence is proved and whose norms are properly bounded.
- Strict equivalences preserve complete eigenstructures of matrix pencils.
- This step is NOT needed for block Kronecker pencils without the zero block.

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is a **strong block minimal bases pencil** with degrees of the dual minimal bases equal to ε and η (the unperturbed ones) and matrix polynomial

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A few words on the system of matrix equations in Step 1

Notation: $L_k(\lambda) \otimes I_\ell = \lambda F_{k\ell} - E_{k\ell}$ and $\Delta\mathcal{L}_{ij}(\lambda) = \lambda\Delta B_{ij} + \Delta A_{ij}$.

The system for the unknown matrices C and D is

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- It is underdetermined: more entries of C and D than scalar equations.
- We extend classical techniques used by Stewart (1972) in the study of perturbation bounds for invariant and deflating subspaces of matrices and pencils, which are valid only for determined matrix equations.
- In this way, we prove that the system is consistent and find a convenient bound for the norm of one of its solutions:

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Discussion of the perturbation bounds for block Kronecker pencils

$$\mathcal{L}(\lambda) = \left[\begin{array}{c|c} \lambda M_1 + M_0 & L_\eta(\lambda)^T \otimes I_m \\ \hline L_\varepsilon(\lambda) \otimes I_n & 0 \end{array} \right].$$

$$\frac{\|\Delta P(\lambda)\|_F}{\|P(\lambda)\|_F} \leq \underbrace{68 d^{5/2} \frac{\|\mathcal{L}(\lambda)\|_F}{\|P(\lambda)\|_F} (1 + \|\lambda M_1 + M_0\|_F + \|\lambda M_1 + M_0\|_F^2)}_{C_{P,\mathcal{L}}} \frac{\|\Delta \mathcal{L}(\lambda)\|_F}{\|\mathcal{L}(\lambda)\|_F}.$$

- It can be proved that if $\|P(\lambda)\|_F \ll 1$ or $\|P(\lambda)\|_F \gg 1$, then $C_{P,\mathcal{L}} \gg 1$,
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- Therefore, for getting “backward stability” from Block Kronecker linearizations, one needs to normalize the matrix poly $\|P(\lambda)\|_F = 1$ and to use pencils such that $\|\lambda M_1 + M_0\|_F \approx \|P(\lambda)\|_F$, then

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$$\frac{\|\Delta P(\lambda)\|_F}{\|P(\lambda)\|_F} \leq \underbrace{68 d^{5/2} \frac{\|\mathcal{L}(\lambda)\|_F}{\|P(\lambda)\|_F} (1 + \|\lambda M_1 + M_0\|_F + \|\lambda M_1 + M_0\|_F^2)}_{C_{P,\mathcal{L}}} \frac{\|\Delta \mathcal{L}(\lambda)\|_F}{\|\mathcal{L}(\lambda)\|_F}.$$

- It can be proved that if $\|P(\lambda)\|_F \ll 1$ or $\|P(\lambda)\|_F \gg 1$, then $C_{P,\mathcal{L}} \gg 1$,
- and that, if $\|\lambda M_1 + M_0\|_F \gg 1$, then $C_{P,\mathcal{L}} \gg 1$.
- Therefore, for getting “backward stability” from Block Kronecker linearizations, one needs to normalize the matrix poly $\|P(\lambda)\|_F = 1$ and to use pencils such that $\|\lambda M_1 + M_0\|_F \approx \|P(\lambda)\|_F$, then

$$\frac{\|\Delta P(\lambda)\|_F}{\|P(\lambda)\|_F} \lesssim d^3 \sqrt{m+n} \frac{\|\Delta \mathcal{L}(\lambda)\|_F}{\|\mathcal{L}(\lambda)\|_F}.$$

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- 1 Introduction
- 2 Goals of the talk
- 3 Block Kronecker pencils
- 4 Strong block minimal bases pencils
- 5 The solution of the perturbation problem
- 6 Conclusions**

- We have proved that the computation of the complete eigenstructure of a matrix polynomial $P(\lambda)$ (regular or singular, square or rectangular)
- via block Kronecker pencils **is backward stable from the polynomial point of view**
- **if $\|P(\lambda)\|_F = 1$ and $\|\lambda M_1 + M_0\|_F \approx \|P(\lambda)\|_F$.**
- This proves, in particular, for the first time “global backward stability” for all Fiedler pencils.
- The new perturbation analysis presents a number of novel features and establishes a framework that can be generalized to other linearizations.
- In particular, we are currently advancing in several “global structured backward error analyses” for structured complete polynomial eigenproblems.

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