

Compactly supported reconstruction functions in average sampling: A matrix pencil approach

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Sampling in a shift-invariant space

$$f \in V_\varphi^2 := \left\{ \sum_{n \in \mathbb{Z}} a_n \varphi(t - n) : \{a_n\} \in \ell^2(\mathbb{Z}) \right\} \subset L^2(\mathbb{R}).$$



Riesz basis

$$\{ \mathcal{L}f(n) \}_{n \in \mathbb{Z}} \xrightarrow{\mathcal{L}f := f * h} f(t) = \sum_{n \in \mathbb{Z}} \mathcal{L}f(n) S_{\mathcal{L}}(t - n)$$

Oversampling

$$\{\mathcal{L}f(n)\}_{n \in \mathbb{Z}} \xrightarrow{r < s} \left\{ \mathcal{L}f\left(\frac{r}{s}n\right) \right\}_{n \in \mathbb{Z}}$$

$$\mathcal{L}_j f(t) := \mathcal{L}f\left(t + \frac{r}{s}(j-1)\right) \quad (1 \leq j \leq s).$$

$$f(t) = \sum_{j=1}^s \sum_{n \in \mathbb{Z}} \mathcal{L}_j f(rn) S_j(t - rn)$$

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Hypotheses

$\varphi, \mathcal{L}\varphi$ compactly supported.

$$g_j(\omega) := \sum_{n \in \mathbb{Z}} \mathcal{L}_j \varphi(n) e^{-2\pi i n \omega} \in L^\infty(0, 1), \quad j = 1, 2, \dots, s$$

$$\mathbf{G}(\omega) := \begin{pmatrix} g_1(\omega) & g_1(\omega + \frac{1}{s}) & \cdots & g_1(\omega + \frac{r-1}{s}) \\ \vdots & \vdots & \ddots & \vdots \\ g_s(\omega) & g_s(\omega + \frac{1}{s}) & \cdots & g_s(\omega + \frac{r-1}{s}) \end{pmatrix}$$

$s \times r$

Trigonometric polynomials

An equivalent problem

Find an $r \times s$ matrix $\mathbf{A}(\omega)$ whose entries are trigonometric polynomials and such that

$$\mathbf{A}(\omega)\mathbf{G}(\omega) = \mathbf{I}_r, \quad \omega \in [0, 1].$$

- 1 A. G. García and G. Pérez-Villalón. Dual frames in $L^2(0, 1)$ connected with generalized sampling in shift-invariant spaces. *Appl. Comput. Harmon. Anal.*, 20(3):422–433, 2006.
- 2 A. G. García, M. A. Hernández-Medina and G. Pérez-Villalón. Oversampling and reconstruction functions with compact support. *J. Comp. Appl. Math.*, 227:245–253, 2009.

Reason

$$\mathbf{A}_{[1,:]}(\omega) =: (\mathbf{a}_1(\omega), \mathbf{a}_2(\omega), \dots, \mathbf{a}_s(\omega))$$

$$S_j(t) = r \sum_{n \in \mathbb{Z}} \hat{\mathbf{a}}_j(n) \varphi(t - n), \quad (t \in \mathbb{R}),$$

$$\hat{\mathbf{a}}_j(n) = \int_0^1 \mathbf{a}_j(\omega) e^{-2\pi i n \omega} d\omega, \quad (1 \leq j \leq s).$$

Existence of $A(\omega)$

There exists a solution



$$\text{rank } \mathbf{G}(\omega) = r \quad \forall \omega \in \mathbb{R}$$

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Towards a matrix pencil

We preserve the rank

Same rank

$$\mathbf{G}(\omega) \rightsquigarrow \mathbb{G}(z) \rightsquigarrow \mathbb{G}(z) \rightsquigarrow \widehat{\mathbb{G}}(z) \rightsquigarrow \widetilde{\mathbb{G}}(z) \rightsquigarrow \mathcal{A}^\top - \lambda \mathcal{B}^\top$$

$$\mathbf{G}(\omega) = \mathbb{G}(e^{-2\pi i \omega})$$

$$\widehat{\mathbb{G}}(z) = \mathbb{G}(z) \Omega_r^{-1}$$

$$\lambda = z^r$$

$$\text{supp}(\mathcal{L}\varphi) \subseteq [0, N]$$

$$1 < N \leq r$$

$$\mathbb{G}(z) = \mathbb{G}(z) \text{diag}[(W^{j-1}z)^{r-1}]_j$$

$$\widetilde{\mathbb{G}}(z) = \widehat{\mathbb{G}}(z) \text{diag}[z^{1-j}]_j$$

Remark

$$\tilde{\mathcal{G}}(\lambda) = (\mathbb{M}(\lambda) \quad \mathcal{G})$$

$$\text{rank } \mathcal{G} = r - N + 1 \quad \implies \exists R \in \mathbb{C}^{s \times s} \mid R\mathcal{G} = \begin{pmatrix} \mathcal{G}' \\ \mathbf{0} \end{pmatrix}$$

$$R\tilde{\mathcal{G}}(\lambda) = \begin{pmatrix} M_1 - \lambda N_1 & \mathcal{G}' \\ M_2 - \lambda N_2 & \mathbf{0} \end{pmatrix}$$

The main result

Existence of solution

Theorem

$\text{rank}(G(z)) = r$ for all $z \in \mathbb{C} \setminus \{0\}$ if and only if the following statements hold

- ① $\text{rank } \mathcal{G} = r - N + 1$.
- ② The *Kronecker Canonical Form* (KCF) of the matrix pencil $M_2 - \lambda N_2$ has not right singular part and the only possible finite eigenvalue is $\mu = 0$.

Using the GUPTRI form of a matrix pencil

Advantages

- ① The needed information about $M_2 - \lambda N_2$ can be retrieved.
- ② We do not need to compute the KCF of the matrix pencil.
- ③ The GUPTRI (General UPper TRIangular) form can be stably computed. (J. Demmel and B. Kågström, 1993; P. Van Dooren, 1979 and 1981).

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Looking for a solution

We use the matrix pencil

$$\tilde{\mathbb{L}}(\lambda)(\mathcal{A}^\top - \lambda\mathcal{B}^\top) = \mathbf{I}_r \quad \iff \quad (\mathcal{A} - \lambda\mathcal{B})\tilde{\mathbb{L}}(\lambda)^\top = \mathbf{I}_r$$

$$[\tilde{\mathbb{L}}(\lambda)^\top]_j = \mathbf{L}_j^0 + \mathbf{L}_j^1\lambda^1 + \cdots + \mathbf{L}_j^v\lambda^v = \sum_{k=0}^v \mathbf{L}_j^k\lambda^k$$

$$\mathcal{A}\mathbf{L}_j^0 + \sum_{k=1}^v \left(\mathcal{A}\mathbf{L}_j^{p+k} - \mathcal{B}\mathbf{L}_j^{k-1} \right) \lambda^k - \mathcal{B}\mathbf{L}_j^v\lambda^{v+1} = \mathbf{I}_r^j,$$

Looking for a solution

We should solve several tied linear systems

$$\left. \begin{array}{lcl}
 \mathcal{A}L_j^0 & = & I_r^j \\
 \mathcal{A}L_j^1 & = & \mathcal{B}L_j^0 \\
 \vdots & \vdots & \vdots \\
 \mathcal{A}L_j^k & = & \mathcal{B}L_j^{k-1} \\
 \vdots & \vdots & \vdots \\
 \mathcal{A}L_j^v & = & \mathcal{B}L_j^{v-1} \\
 \mathcal{B}L_j^v & = & \mathbf{0}
 \end{array} \right\}$$

What is the minimum v which allows us to solve these tied systems at once?

Looking for a solution

Theorem

Suppose that the $(r + 1) \times r$ -singular matrix pencil $\mathcal{A}^\top - \lambda \mathcal{B}^\top$ satisfies the following conditions:

- It has no finite eigenvalues.
- $\text{rank}(\mathcal{A}^\top) = r$.
- $\text{rank}(\mathcal{B}^\top) = N - 1$.
- $\text{rank} \left[\begin{pmatrix} -\mathcal{B} & \mathbf{0} \\ \mathcal{A} & -\mathcal{B} \end{pmatrix} \right] = r + N - 1$.

Then, the $Nr \times (N - 1)(r + 1)$ -matrix $G_r(N - 2)$ has maximum rank, i.e., $(N - 1)(r + 1)$.

Optimality problem

- We have found a matrix algebraic polynomial with $N - 1$ terms as solution of the problem.
- The number of terms of the solution is intimately related to the support of the reconstruction functions.
- What is the minimum number of nonzero terms that a solution could have? We consider two options:
 - We have some null coefficients.
 - The process can be finished for $\nu < N - 2$.

Hypotheses that \mathcal{A} verifies

Sufficient condition

$$\mathcal{A} = \begin{array}{c} \begin{array}{|c|c|c|c|c|c|c|} \hline 0 & 0 & \dots & 0 & 0 & \dots & 0 \\ \hline \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ \hline 0 & 0 & \dots & 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 & 0 & \dots & \bullet \\ \hline \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 & \bullet & \dots & \square \\ \hline \end{array} & \begin{array}{|c|c|c|} \hline 0 & \dots & \bullet \\ \hline \vdots & \ddots & \vdots \\ \hline \bullet & \dots & \square \\ \hline \vdots & \ddots & \vdots \\ \hline \square & \dots & \square \\ \hline \end{array} \\ \hline \begin{array}{|c|c|c|c|c|c|c|} \hline 0 & 0 & \dots & \bullet & \square & \dots & \square \\ \hline \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ \hline 0 & \bullet & \dots & \square & \square & \dots & \square \\ \hline \end{array} & \begin{array}{|c|c|c|} \hline \square & \dots & \bullet \\ \hline \vdots & \ddots & \vdots \\ \hline \bullet & \dots & 0 \\ \hline \end{array} \\ \hline \end{array} \begin{array}{l} N-1 \\ r-N+1 \end{array}$$

$1 \qquad N-1 \qquad r-N+1$

Hypotheses that \mathcal{B} verifies

Sufficient condition

$$\mathcal{B} = \begin{array}{c} \begin{array}{|cccccc|ccc} \hline \square & \square & \dots & \square & \square & \square & \bullet & 0 & \dots & 0 \\ \square & \square & \dots & \vdots & \vdots & \dots & \vdots & \vdots & \dots & \vdots \\ \square & \square & \dots & \square & \bullet & \dots & 0 & 0 & \dots & 0 \\ \square & \square & \dots & \bullet & 0 & \dots & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \dots & \vdots & \vdots & \dots & \vdots & \vdots & \dots & \vdots \\ \square & \bullet & \dots & 0 & 0 & \dots & 0 & 0 & \dots & 0 \\ \hline 0 & 0 & \dots & 0 & 0 & \dots & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \dots & \vdots & \vdots & \dots & \vdots & \vdots & \dots & \vdots \\ 0 & 0 & \dots & 0 & 0 & \dots & 0 & 0 & \dots & 0 \\ \hline \end{array} & \begin{array}{c} N-1 \\ r-N+1 \end{array} \end{array}$$

$1 \qquad \qquad \qquad N-1 \qquad \qquad \qquad r-N+1$

Conclusions

Optimality

- If $\nu < N - 2$, there exists no solution.
- If $\nu = N - 2$, there exists a unique solution.
- If $\nu > N - 2$, there exist several solutions.
- Moreover, if there exists any solution, it has at least $N - 1$ nonzero consecutive terms.

A toy model involving the quadratic B-spline

The generator

$$N_3(t) = \chi_{[0,1)} * \chi_{[0,1)} * \chi_{[0,1)}$$

$$\varphi(t) = N_3(t) = \frac{t^2}{2} \chi_{[0,1)}(t) + \left(-\frac{3}{2} + 3t - t^2\right) \chi_{[1,2)}(t) + \frac{1}{2}(3-t)^2 \chi_{[2,3)}(t).$$

$$\mathcal{L}f = f \quad ; \quad \text{supp } \mathcal{L}\varphi \subseteq [0, 3] \quad (N = 3)$$

$$\text{Samples: } f\left(\frac{4}{5}n\right) \quad (r = 4, s = 5)$$

A toy model involving the quadratic B-spline

The functions $g_j(z)$

$$g_1(z) = \frac{1}{2}z + \frac{1}{2}z^2$$

$$g_2(z) = \frac{8}{25} + \frac{33}{50}z + \frac{1}{50}z^2$$

$$g_3(z) = \frac{9}{50}z^{-1} + \frac{37}{50} + \frac{2}{25}z$$

$$g_4(z) = \frac{2}{25}z^{-2} + \frac{37}{50}z^{-1} + \frac{9}{50}$$

$$g_5(z) = \frac{1}{50}z^{-3} + \frac{33}{50}z^{-2} + \frac{8}{25}z^{-1}$$

A toy model involving the quadratic B-spline

The matrix $\hat{\mathbb{G}}(z)$

$$\hat{\mathbb{G}}(z) = \begin{pmatrix} \frac{1}{2}z^4 & \frac{1}{2}z^5 & 0 & 0 \\ \frac{33}{50}z^4 & \frac{1}{50}z^5 & 0 & \frac{8}{25}z^3 \\ \frac{2}{25}z^4 & 0 & \frac{9}{50}z^2 & \frac{37}{50}z^3 \\ 0 & \frac{2}{25}z & \frac{37}{50}z^2 & \frac{9}{50}z^3 \\ \frac{1}{50} & \frac{33}{50}z & \frac{8}{25}z^2 & 0 \end{pmatrix}$$

A toy model involving the quadratic B-spline

The matrix $\tilde{G}(z)$

$$\tilde{G}(z) = \hat{G}(z) \operatorname{diag} [1, z^{-1}, z^{-2}, z^{-3}]$$

$$\tilde{G}(z) = \begin{pmatrix} \frac{1}{2}z^4 & \frac{1}{2}z^4 & 0 & 0 \\ \frac{33}{50}z^4 & \frac{1}{50}z^4 & 0 & \frac{8}{25} \\ \frac{2}{25}z^4 & 0 & \frac{9}{50} & \frac{37}{50} \\ 0 & \frac{2}{25} & \frac{37}{50} & \frac{9}{50} \\ \frac{1}{50} & \frac{33}{50} & \frac{8}{25} & 0 \end{pmatrix}$$

A toy model involving the quadratic B-spline

The matrix pencil

$$\lambda = z^4$$

$$\mathcal{A}^\top - \lambda \mathcal{B}^\top = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{8}{25} \\ 0 & 0 & \frac{9}{50} & \frac{37}{50} \\ 0 & \frac{2}{25} & \frac{37}{50} & \frac{9}{50} \\ \frac{1}{50} & \frac{33}{50} & \frac{8}{25} & 0 \end{pmatrix} - \lambda \begin{pmatrix} \frac{-1}{2} & \frac{-1}{2} & 0 & 0 \\ \frac{-33}{50} & \frac{-1}{50} & 0 & 0 \\ \frac{-2}{25} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

A toy model involving the quadratic B-spline

Solving the linear systems

$$\begin{pmatrix} -\mathcal{B} & \mathbf{0} \\ \mathcal{A} & -\mathcal{B} \\ \mathbf{0} & \mathcal{A} \end{pmatrix} \begin{pmatrix} \ell_j^1 \\ \ell_j^0 \end{pmatrix} = \begin{pmatrix} \mathbf{0} \\ \mathbf{0} \\ \mathbf{I}_4^j \end{pmatrix}, \quad j = 1, 2, 3, 4$$

A toy model involving the quadratic B-spline

The left-inverse matrix

$$\tilde{\mathbb{L}}(\lambda)^\top = \begin{pmatrix} \frac{123034939}{27456} & \frac{-125425}{36} & \frac{28925}{18} & \frac{-825}{2} & 50 \\ \frac{-3949115}{27456} & \frac{4025}{36} & \frac{-925}{18} & \frac{25}{2} & 0 \\ \frac{227683}{13728} & \frac{-925}{72} & \frac{50}{9} & 0 & 0 \\ \frac{-19483}{4576} & \frac{25}{8} & 0 & 0 & 0 \end{pmatrix} + \lambda \cdot \begin{pmatrix} \frac{-18911}{9152} & \frac{472775}{9152} & \frac{-472775}{1144} & \frac{16547125}{10296} & \frac{-286974425}{82368} \\ \frac{607}{9152} & \frac{-15175}{9152} & \frac{15175}{1144} & \frac{-531125}{10296} & \frac{9211225}{82368} \\ \frac{-35}{4576} & \frac{875}{4576} & \frac{-875}{572} & \frac{30625}{5148} & \frac{-531125}{41184} \\ \frac{9}{4576} & \frac{-225}{4576} & \frac{225}{572} & \frac{-875}{572} & \frac{15175}{4576} \end{pmatrix}$$

A toy model involving the quadratic B-spline

Finally, the compact supported reconstruction functions

$$S_1(t) := \frac{123034939}{27456} \varphi(t) - \frac{3949115}{27456} \varphi(t+1) + \frac{227683}{13728} \varphi(t+2) - \frac{19483}{4576} \varphi(t+3) \\ - \frac{18911}{9152} \varphi(t-4) + \frac{607}{9152} \varphi(t-3) - \frac{35}{4576} \varphi(t-2) + \frac{9}{4576} \varphi(t-1)$$

$$S_2(t) := -\frac{125425}{36} \varphi(t) + \frac{4025}{36} \varphi(t+1) - \frac{925}{72} \varphi(t+2) + \frac{25}{8} \varphi(t+3) \\ + \frac{472775}{9152} \varphi(t-4) - \frac{15175}{9152} \varphi(t-3) + \frac{875}{4576} \varphi(t-2) - \frac{225}{4576} \varphi(t-1)$$

$$S_3(t) := \frac{28925}{18} \varphi(t) - \frac{925}{18} \varphi(t+1) + \frac{50}{9} \varphi(t+2) \\ - \frac{472775}{1144} \varphi(t-4) + \frac{15175}{1144} \varphi(t-3) - \frac{875}{572} \varphi(t-2) + \frac{225}{572} \varphi(t-1)$$

$$S_4(t) := -\frac{825}{2} \varphi(t) + \frac{25}{2} \varphi(t+1) \\ - \frac{16547125}{10296} \varphi(t-4) - \frac{531125}{10296} \varphi(t-3) + \frac{30625}{5148} \varphi(t-2) - \frac{875}{572} \varphi(t-1)$$

$$S_5(t) := 50\varphi(t) \\ - \frac{286974425}{82368} \varphi(t-4) + \frac{9211225}{82368} \varphi(t-3) - \frac{531125}{41184} \varphi(t-2) + \frac{15175}{4576} \varphi(t-1)$$